

# HallScrew HSS 3200 Series

# Semi-hermetic Integral Single Screw Compressors

# HSS 3216, HSS 3218, HSS 3220 and HSS 3221

**Application Manual** 





#### J & E Hall International<sup>®</sup> 2011

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## 1. General Description

The J & E Hall International HSS 3200 series of semi-hermetic integral compressors are the latest addition to the HallScrew family of oil injected, positive displacement, single screw compressors. Reflecting the very latest innovations in screw compressor technology, they are designed for incorporation into factory built DX chillers using R407c, R134a or R22 with independent refrigerant circuits for each compressor.

HSS 3200 series compressors are capable of operating without cooling over a limited range, but when indicated, cooling by liquid injection can be employed.

#### 1.1. Main Features

- For use with R407c, R134a and R22.
- Integral oil separator.
- Designed and tested to international standards.
- Robust construction.
- Improved machine clearance control for maximum efficiency.
- Oil injected for maximum reliability.
- Balanced loading on main bearings for maximum bearing life.
- Enhanced slide valve geometry for capacity modulation with minimum loss of efficiency. Infinite adjustment between maximum (100 %) and minimum load (nominal 25 %).
- Simple, built-in capacity control using two solenoid valves.
- Economiser facility provided to improve operating efficiency, especially at high compression ratios.

For further information refer to publication 2-129 Economiser Facility For HallScrew Compressors.

- Internal suction/discharge safety relief valve (not UL approved).
- Integral discharge check valve. Combined discharge stop valve, check valve and head pressure control valve available as optional extra (R134a applications only).
- High efficiency built in 3 phase, 2 pole motor unit for reliable operation. Two different motor power options. Available for 50 Hz or 60 Hz operation.
- Motor designed for star/delta or soft-start.
- Thermistor high temperature protection to motor.
- Thermistor discharge gas high temperature protection.
- Built-in oil filter.

#### 1.2. Construction

The compressor is driven by a specially designed motor mounted on one end of the compressor main shaft.



The compressor consists of three cast-iron castings which are bolted together. The first casting, the main casing, encloses the motion work comprising the main rotor and star rotors. The second casting, the motor housing, encloses the 3 phase, 2 pole motor. Returning suction vapour flows around the stator/rotor unit, cooling the windings in the process, before entering the main rotor flutes. The third casing provides three functions: a delivery end cover, a separator and an oil filter housing.

Thermistor probes, buried deep in each phase of the stator windings, provide protection against high temperatures. Phase wiring and thermistor terminations are made to a terminal plate inside an enclosure mounted on the top of the motor housing.

The motion work, i.e. that part of the machine which performs the compression function, consists of three rotating parts; there are no eccentric or reciprocating motions. These fundamental components comprise the cylindrical main rotor in which are formed six-start, helically grooved screw threads with a spherical (hourglass) root form. The main rotor meshes with two identical toothed wheels each having eleven teeth. These wheels (or 'star rotors' as they are called owing to their shape), are made from a special synthetic material. They are located in a single plane diametrically opposite each other on either side of the main rotor, with their axes at right angles to the main rotor axis. As the main rotor turns, it imparts a freely rotating motion to the star rotors.

The star rotors are supported by metal backings which are cast in onepiece with the star rotor shafts. Although they are located in place on their backings, the stars are allowed to 'float' a small amount in a rotational sense. This floating action, combined with the low inertia and negligible power transmission between the main rotor and star rotors, ensures compliance of the star/main rotor combination. The star rotor shafts are supported at each end by taper roller bearings.

The main rotor is supported on a shaft the other end of which carries the motor rotor. The shaft is supported by an arrangement of rolling element bearings at three positions. This entire assembly is dynamically balanced.

The main rotor and star rotors are housed inside the main casing. The inside of this main casing has a somewhat complex shape, but essentially consists of a specially shaped cylindrical annulus, which encloses the main rotor leaving a small clearance. Part of the annulus is cutaway at the suction end to allow the suction gas to enter the rotor. In addition there are two slots, one each side, to allow the star teeth to mesh with the main rotor flutes. The discharge ports (one for each star), are positioned at the other end of the annulus. These ports convey the compressed gas out of the compressor via the discharge outlet. Except for the discharge ports and oil management system, suction pressure prevails throughout the main casing.

Side covers are provided to allow easy access to the star rotors, star rotor shafts and bearings, without disturbing working tolerances. The discharge end cover can also be removed to inspect the capacity control mechanism.

The compressor is fitted with an integral suction strainer, built into the suction end cover, designed to trap any dirt circulating with the refrigerant which might otherwise enter and damage the compressor.



The integral oil separator is bolted to the rear of the main casing. The impingement type separator is fitted with a knitted stainless steel mesh element which removes the majority of entrained oil from the discharge gas stream. Two sight-glasses, one each side, are provided to check the level of oil in the reservoir at the bottom of the separator. The reservoir is fitted with a 250 W heater.

The integral oil separator is fitted with a built-in discharge check valve. As an option, for R134a applications only, the discharge connection can be fitted with a specially designed valve which combines the functions of a stop valve, non-return valve and head pressure control valve in one compact assembly; for further details refer to 6. 3N1 Three Function Valve for HSS 3200 Series Compressors (R134a Only). The 3N1 valve replaces the non-return valve otherwise fitted in the oil separator housing.

#### 1.2.1. Internal Relief Valve

The compressor is fitted with an internal suction/discharge relief valve to protect against overpressure, for example, in the event of operation with a closed delivery valve in the system. Adequate system relief valves designed to match the plant design pressure must be retained.

#### 1.3. The Compression Process

With single screw compressors the suction, compression and discharge process occurs in one continuous flow at each star wheel. In this process the suction gas fills the profile between the rotor, star tooth and casing. The volume is steadily reduced and the refrigerant gas thereby compressed. The high-pressure gas is discharged through a port, the size and geometry of which is determined by the internal volume ratio (ratio of the volume of gas at the start and finish of compression). This volume ratio must have a defined relationship to the mass flow and the working pressure ratio, to avoid losses in efficiency due to over and under compression.

As the HallScrew is a positive displacement compressor, there are three separate stages in the compression cycle: suction, compression and discharge. These are illustrated in Fig 1.



#### 1. and 2. Suction

Main rotor flutes 'a', 'b' and 'c' are in communication at one end with the suction chamber via the bevelled rotor end face, and are sealed at the other end by the teeth of star rotor A. As the main rotor turns, the effective length of the flutes increases with a corresponding increase in the volume open to the suction chamber: Diagram 1 clearly shows this process. As flute 'a' assumes the position of flutes 'b' and 'c' its volume increases, inducing suction vapour to enter the flute.

Upon further rotation of the main rotor , the flutes which have been open to the suction chamber engage with the teeth of the other star rotor. This coincides with each flute being progressively sealed by the main rotor. Once the flute volume is closed off from the suction chamber, the suction stage of the compression cycle is complete.

#### 3. Compression

As the main rotor turns, the volume of gas trapped within the flute is reduced as the length of the flute shortens and compression occurs.

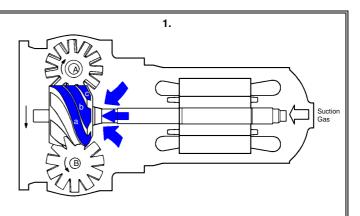
#### 4. Discharge

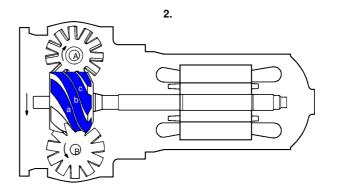
flute/star tooth in turn.

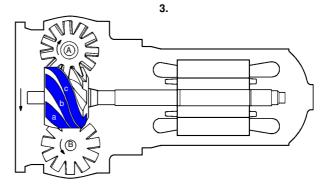
As the star rotor tooth approaches the end of a flute, the pressure of the trapped vapour reaches a maximum value occurring when the leading edge of the flute begins to overlap the triangular shaped discharge port. Compression immediately ceases as the gas is delivered into the discharge manifold. The star rotor tooth continues to scavenge the flute until the flute volume is reduced to zero. This compression process is repeated for each

While the compression process described above is occurring in the upper half of the compressor, there is an identical process taking place simultaneously in the lower half using star B, thus each main rotor flute is used twice per rotor revolution (one by one tooth in each star). The compression process may be likened to an assembly of six double-acting cylinders (the main rotor flutes) in which the star rotor teeth move as pistons (always in the same direction).

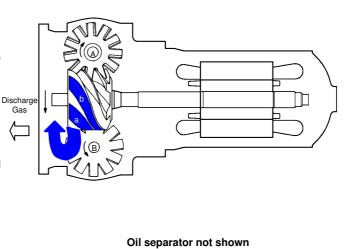
**Fig 1 Compression Process** 







4.



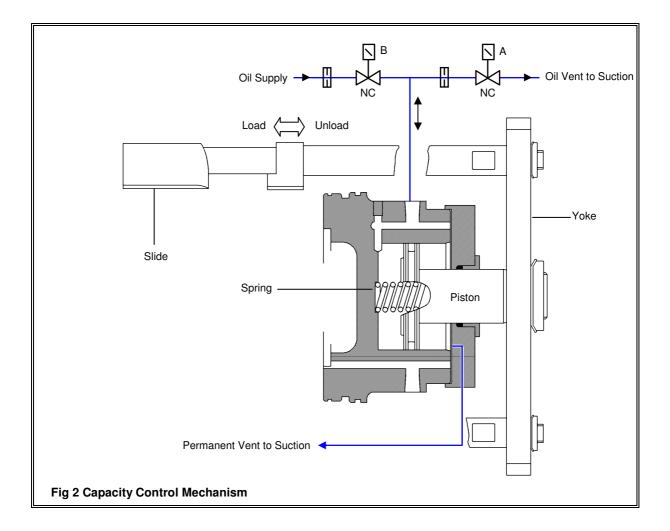
# 2. Capacity Control and Volume Ratio

HallScrew HSS 3200 series compressors are provided with infinitely variable capacity control as standard.

Since the HallScrew compressor utilises fixed intake and discharge ports instead of valves, the overall compression ratio is determined by the configuration of these ports. The degree of compression is governed by the ratio between the flute volume when it is sealed off by the star tooth at the beginning of the compression process, to that immediately before the discharge port is uncovered. This is known as the built-in volume ratio ( $V_R$ ) and is an important characteristic of all fixed-port compressors.

In order to achieve maximum efficiency, the pressure within the flute volume at the end of the compression process should equal the pressure in the discharge line at the instant the flute volume opens to discharge. Should these conditions not prevail, either overcompression or undercompression will occur, both of which result in internal losses. Although in no way detrimental to the compressor, inefficient compression will increase power consumption.

The compressor is fitted with a pair of sliding valves, one for each half of the symmetrical compression process. These valves reduce pumping capacity by delaying the sealing of the flute volume together with the opening of the discharge port, altering the effective length of the main rotor flutes. The valves permit stepless capacity control down to approximately 25 % of full load (actual minimum value varies with operating conditions).





Each slide valve is housed in a semicircular slot in the wall of the annular ring which encloses the main rotor. As the slide valve travels axially from the full load position it uncovers a port, which vents part of the gas trapped in the main rotor flute back to suction, before compression can begin. When the flute has passed beyond the port, compression commences with a reduced volume of gas. However, a simple bypass arrangement without any further refinement would produce an undesirable fall in the effective volume ratio which in turn causes under compression and inefficient part load operation. To overcome this problem, the slide valve is shaped so that it delays the opening of the discharge port at the same time as the bypass slot is created.

#### 2.1. Slide Valve Actuation

The method of operation is illustrated in Fig 2.

The capacity control slides valves are joined together by a yoke which is connected to a hydraulic piston, housed inside a cylinder and mounted internally at the discharge end of the compressor.

Variation in compressor pumping capacity is achieved by altering the forces acting on the slide valve/piston assembly.

Internal drillings communicate pressurised oil to the capacity control cylinder and vent the oil from the cylinder. The flow of oil is controlled by two separate solenoid valves, A and B; the solenoids are normally closed (NC), energise to open.

The piston cylinder incorporates a spring. When the compressor is running, a pressure difference is created across the slide valves: discharge pressure acts on one end of the slides, suction pressure at the other end. This differential pressure creates a force on the slides tending to drive them towards the maximum load position. Oil pressure assisted by the spring force acting on the piston, creates an opposing force tending to move the slides towards the minimum load position.

When the compressor is required to stop, or if the compressor is stopped before minimum load is attained, for example, a fault condition or operating emergency, the pressures within the compressor equalise. Under these conditions the spring moves the piston and slide valves to the minimum load position, thereby ensuring that the compressor always starts at minimum load.

#### 2.1.1. Minimum Load Interlock

Starting at minimum load minimises motor starting current and starting torque. This in turn minimises stresses on the motor and mechanical parts, and also reduces the load on the power supply network.

The control system must be interlocked to prevent the compressor starting unless the linear variable displacement transducer (LVDT) provides an 'at minimum load' permit start signal.

#### 2.2. Continuously Variable Capacity Control

The plant controller energises and de-energises the solenoids to control the rate of loading/unloading. These signals must be provided by a suitable pulse timer with a minimum pulse length of 0.1 to 0.5 seconds, depending upon the accuracy of control required.

Solenoid A is energised to load the compressor, solenoid B is energised to unload.





#### 2.2.1. Controlled Stop

When the compressor is required to stop from a loaded condition, solenoid valve B is energised (open). High pressure oil is admitted to the capacity control cylinder. Oil pressure supplements the force of the spring acting on the unload side of the piston. The combined force is sufficient to overcome the action of the suction/discharge differential pressure and move the slide valves towards the minimum load position.

#### 2.2.2. Uncontrolled Stop

When an uncontrolled stop occurs: safety control operating, emergency stop or power failure, the unloading spring automatically returns the slide valves to minimum load.

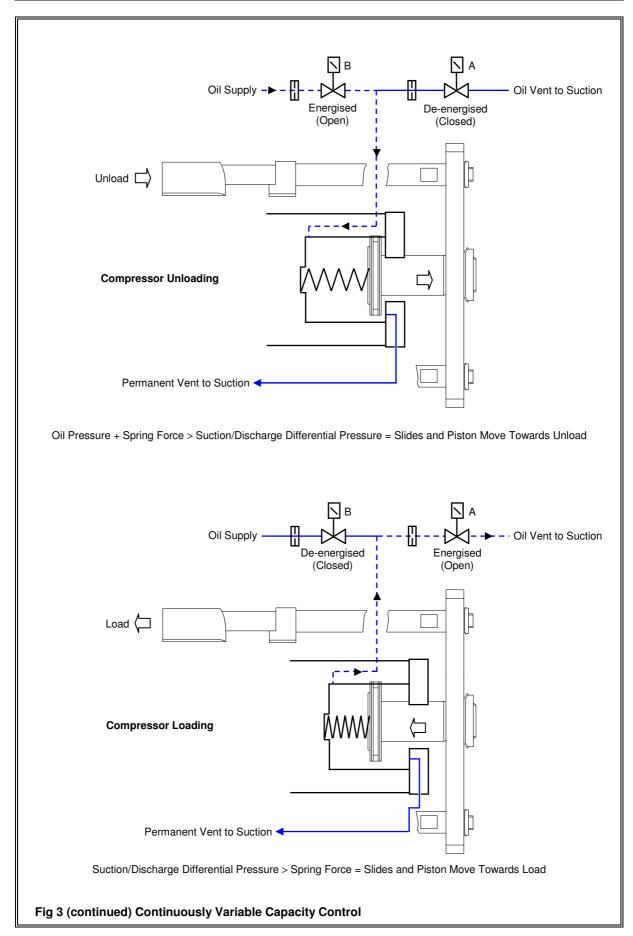
Unlike a controlled stop, unless the compressor was at minimum load before the uncontrolled stop occurred, the capacity control cylinder may contain some refrigerant vapour instead of being completely filled with oil. In this event a hydraulic lock will not be present and uncontrolled loading may occur on restarting.

This undesirable behaviour can be minimised by arranging for solenoid valve B to energise (open):

- If a compressor trip, emergency stop or power failure occurs.
- 60 seconds before (but not during) compressor start-up. Energised until the compressor is required to load; refer to Fig 3.

CAPACITY CONTROL ACTION	SOLENOID VALVE A	<sup>1</sup> SOLENOID VALVE B
Load compressor		
Oil is vented from the capacity control cylinder. The action of the suction/ discharge differential pressure on the slide/piston assembly overcomes the force of the unloading spring and moves the slide valves towards the maximum load position.	Energise (open)	De-energise (close)
Unload compressor		
High pressure oil is admitted to the capacity control cylinder. Oil pressure supplements the force of the spring acting on the unload side of the piston. The combined force is sufficient to overcome the action of the suction/discharge differential pressure and move the slide valves towards the minimum load position.	De-energise (close)	Energise (open)
Hold slide valve position		
The slide valve is hydraulically locked at the desired load position.	De-energise (close)	De-energise (close)
	bressor d to Load	
Compressor Stopped - 60 Seconds - 60 Seconds -		───► Time
← Solenoid Valve B Energised (Open) → Solenoid Valve B ← De-energised → (Closed)	Solenoid Valve B Ener Until Compressor Rec	rgised (Open)
<sup>1</sup> Refer to 2.2.2. Uncontrolled Stop.		
Fig 3 Continuously Variable Capacity Control		







#### 2.3. Capacity Control by Inverter Drive

Instead of using the slide valve, compressor capacity can be controlled using a frequency inverter (also know as Variable Speed Drive or Variable Frequency Drive). If an inverter is used, the load/unload solenoid valves need to be controlled to allow the compressor to start at minimum load but load to full load when the compressor is running. There are three methods of achieving this;

- Energise the load solenoid continuously irrespective of whether the compressor is running or not.
- Energise the load solenoid continuously when the compressor is running and the unload solenoid continuously when the compressor is stopped.
- Remove the plunger from the load solenoid valve (only) and do not fit the coils.

When using an inverter, it is of utmost importance that it is both sized and set up correctly.

#### 2.3.1. Inverter Size

The inverter must be sized to deliver the maximum current taken by the compressor motor at the maximum power conditions – in most cases this is during pull down.

#### The current capacity of an inverter drive is not reduced by running at less than synchronous speed.

During pull down, the current can be limited by either using the slide valve to run the compressor unloaded, or by throttling the suction. If it is required to use the slide valve during pull down, then normal manual slide valve control can be used; refer to 2.2. Continuously Variable Capacity Control.

#### 2.3.2. Inverter Set-up

The inverter drive used must have the following facilities as a minimum;

- Load type: constant torque.
- Control method: PID (automatic) with facility for manual frequency control.

Particular attention has to paid to setting up the inverter with the correct minimum frequency, maximum frequency and acceleration time.

Minimum frequency and maximum frequency must be set according to the operating conditions; refer to J & E Hall International.



## 3. Compressor Lubrication, Sealing and Cooling

HSS 3200 series compressors are fitted with an integral oil separator and oil filter.

The oil performs three basic functions:

#### 3.1. Capacity Control Actuation

Oil pressure is used to actuate the compressor capacity control mechanism; refer to 2.1. Slide Valve Actuation.

#### 3.2. Bearing Lubrication

The rolling element bearings used in the construction of the HallScrew compressor require a steady but relatively small supply of oil for satisfactory operation and long life. Oil is supplied either directly via separate oil drillings or indirectly from the injection supply to the bearings.

#### 3.3. Oil Injection for Sealing and Cooling

The third oil supply, which is the predominant oil usage, provides oil for injection to seal the compression process. In the design of the compressor the star rotor teeth must form an effective seal with the flute profiles in the main rotor, while at the same time maintaining a satisfactory operating clearance. The main rotor flute/star tooth profile enables hydrodynamic and hydrostatic actions to combine to provide a wedge of oil at this point. Between the main rotor and the casing, and in several other positions where a pressure differential is separated by two surfaces moving relative to each other, the oil injected provides a sealing film enabling effective compression to take place. The oil also has a silencing effect.

Oil is injected via fixed ports in the casing around the rotor. This provides a variable injection period within the compression process as the compressor unloads. This variation of injection period is so designed as to allow the compressor to operate at lower system pressure differentials at minimum load compared to operation at full load. This provides an element of additional safety during start up at reduced load before full system differentials may be achieved. This arrangement is different to previous HallScrew compressors, in which the compressor was required to load as quickly as possible so that the system pressure difference was built up as quickly as possible. This rapid loading is no longer required. Once normal system pressures have been achieved, oil is injected over a period in the compression process when the pressure of the gas trapped in the flutes is considerably lower than discharge pressure. This means that in the majority of instances the system pressure difference can be used to provide the required oil flow without the need for an oil pump running continuously, while the plant is in operation.

The standard method of compressor cooling, when required, is via liquid refrigerant injection directly into the compressor; refer to 5. Compressor Cooling.



## 4. Oil Support System

HSS 3200 series compressors are fitted with an integral oil separator and oil filter. For most applications, an external oil support system is not necessary; refer to 4.5. External Oil Cooler/Oil Filter.

The system into which the compressor is to be installed must fully comply with the recommendations in 4.1. to 4.6. Failure to do so could result in deterioration of the compressor, both mechanically and functionally.

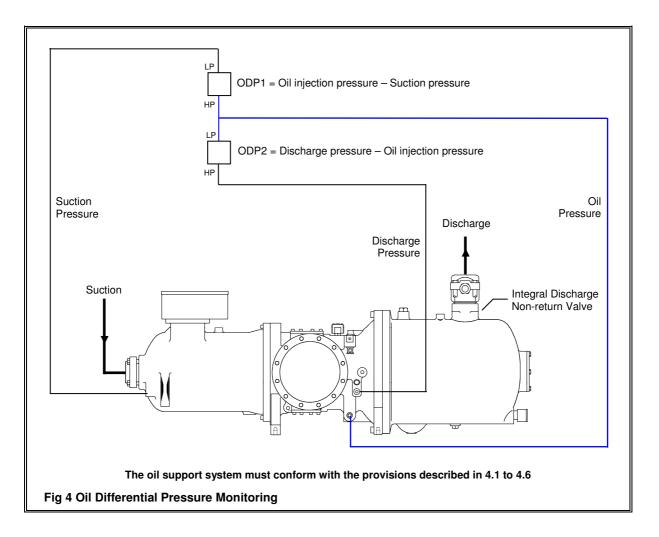
Typical oil support system schematic flow diagrams for different applications can be found in Appendix 2 Oil Support System Schematic Flow Diagrams.

#### 4.1. Internal Oil Drain

An oil drain facility, including a non-return valve (ball type), forms an integral part of HSS 3200 series compressors. Oil which collects inside the compressor casing automatically drains back to the integral oil separator via the internal drain. An external drain line is not required.

#### 4.1.1. Oil Heater

The compressor integral oil separator is fitted with a heater to maintain an oil temperature minimum 20 °C above the ambient temperature, thereby preventing refrigerant migration into the oil and the resultant loss of viscosity and potential foaming. The oil heater must be electrically interlocked to energise when the compressor stops.





#### 4.2. Oil Low Level Sensor (Option)

Provision is made to fit a level sensor to the oil separator at a point corresponding to a dangerously low oil level. The sensor must be electrically interlocked to stop the compressor if the oil level falls to the danger level.

#### 4.3. Oil Differential Pressure Monitoring

As already described in 3. Compressor Lubrication, Sealing and Cooling, HSS 3200 series compressors require an adequate supply of oil for injection, bearing lubrication and capacity control actuation.

Under normal operating conditions this oil is supplied via the difference in pressure between discharge and suction pressures. On starting the suction/discharge pressure differential across the compressor builds rapidly. However, this pressure difference must be monitored to ensure it achieves the correct value within a specified time. Oil differential pressure monitoring must continue all the while the compressor is running in case operating conditions cause the differential to fall to an unacceptable level. Under these conditions operation of the compressor must be prevented or alternative oil injection arrangements made.

The oil system must be protected by monitoring two oil differential pressures: ODP1 and ODP2. Two different methods are available:

- Electro-mechanical oil differential pressure switches.
- Transducers sensing the required pressures, connected to the plant controller with the differential pressure calculation performed by the software programme.

#### 4.3.1. ODP1

This is the differential between oil injection pressure/suction pressure and determines if there is sufficient pressure difference for adequate oil injection to occur.

ODP1 = Oil injection pressure - Suction pressure

Because oil injection takes place into a sealed flute during the compression process an estimate of the pressure in this flute must be made. This pressure is a ratio of the suction pressure and for maximum safety should be taken as twice absolute suction pressure. If ODP1 is sensed by transducers then the pressure ratio from suction to oil should be set to 2. If an oil differential pressure switch is used, this should be set to trip when oil pressure is below twice the maximum operating suction pressure (absolute).

#### Example:

Maximum suction pressure 3.0 bar abs (2 bar g)

Minimum oil pressure  $2 \times 3.0$  bar abs = 6.0 bar abs

Oil differential switch setting (oil pressure – suction pressure)

= 6.0 – 3.0 = 3.0 bar

On start up there is no system pressure differential, therefore, ODP1 must be timed out. The standard time out period is 30 seconds. If ODP1 is not achieved after this period alternative arrangements must be made. Refer to J & E Hall International for advice on the appropriate action.

#### 4.3.2. ODP2

This is the differential across the oil injection line and should initially be set to 2.0 bar in order to prevent operation in the event of a blocked oil filter or similar obstruction in the oil injection line.



ODP2 = Discharge pressure - Oil injection pressure

If it is found that the normal operating ODP2 differential is above 2 bar with a clean filter, then the cut-out differential can be increased accordingly. ODP2 does not need to be timed out.

#### 4.4. Maintaining Discharge Pressure at Start up

Because oil pressure is generated by suction/discharge pressure differential, there is a minimum discharge pressure value which must be maintained in order to ensure adequate and reliable oil flow.

In circumstances where the minimum discharge pressure is difficult to achieve, it is recommend to use the J & E Hall International three function valve; refer to 6. 3N1 Three Function Valve for HSS 3200 Series Compressors (R134a Only).

#### 4.5. External Oil Cooler/Oil Filter

HSS 3200 series compressors are fitted with an internal oil filter which is adequate for factory built chillers for which these compressors are designed, where system cleanliness can be guaranteed. The HSS 3200 series is also designed for liquid injection cooling, where necessary, to control the discharge temperature. High rates of liquid injection will derate the performance, so in these circumstances, particularly with refrigerants R407c and R22 with high condensing temperature, an external oil cooler can be used to enhance efficiency.

If an external oil cooler is to be fitted and/or an external oil filter is preferred, then a special kit is available, part number M330874501, which allows the internal filter to be removed and provides an outlet for the oil to pass through an external circuit; refer to Fig 13. The minimum specification for an external oil filter is shown in Table 1.

	PARAMETER	VALUE				
Filter minimum particle	e size	Down to 5 micron (Beta 5 value >1)				
Filter absolute rating		25 micron (Beta 25 value >75)				
Minimum filter area	Synthetics: felts/glass fibre with in-depth filtration	1500 cm <sup>2</sup>				
Minimum inter area	Paper or cellulose	5000 cm <sup>2</sup>				
Minimum dirt holding o	capacity	>13.5 gm				
Minimum filter elemen	t collapse pressure	20.0 bar				
Complete filter assem	Complete filter assembly maximum clean pressure drop 0.7 bar with oil flow of 50.0 lt/min					
NOTE: All filter components must be suitable for use with the system oil and refrigerant.						
Table 1 External Oil Filter Minimum Specification						

#### 4.6. Lubricating Oils

The choice of lubricant depends on the refrigerant, the type of system and the operating conditions.

For applications using R134a, R407c or other HFC refrigerants, ester lubricants **must** be used. The compressor is supplied already charged with oil, either Emkarate RL68H or ExxonMobil EAL Arctic 68.

For applications using R22, the compressor is supplied already charged with Mobil Arctic 300 mineral oil.



## 5. Compressor Cooling

The standard method of cooling for HSS 3200 series compressors is by direct injection of liquid refrigerant into the compressor main rotor flute, part-way through the compression process.

For further details refer to publication 2-122 Compressor Cooling.

#### 5.1. Deciding if Liquid Injection is Required

As the compressor unloads the condensing temperature decreases because the load on the condenser is reduced. For air conditioning applications in particular (not for process applications), there is a further reduction in condensing temperature associated with the reduced ambient for part load operation. This is added to the reduction in condensing temperature due to the reduced load. There is also a small increase in evaporating temperature.

The No Cooling Load Limit envelopes illustrated in Appendix 3 and the examples in Fig 5 are divided into areas which show the compressor percentage load range for operation without liquid injection cooling.

#### 5.2. Liquid Injection Control and Economiser Connections

#### R134a

The compressor is fitted as standard with a special liquid injection orifice plug in the top liquid injection/economiser connection only. This plug is used for R134a liquid injection cooling only. The bottom connection is fitted with a solid plug.

#### R407c and R22

The standard arrangement for R22 and R407c is to use a thermostatic liquid injection valve. In this case the special orifice plug fitted in the top connection and the blank plug fitted in the bottom connection should be removed.

It may be possible to use the R134a arrangement for R22 and R407C applications with limited maximum condensing temperature (approximately 50 °C SDT), but this must be subject to verification by trial, undertaken by the chiller manufacturer, that the maximum discharge temperature is not exceeded when the maximum liquid injection demand is required (this may be at minimum load). Such trials must be at the chiller development stage (**not on an end user installation**) and must be sanctioned by J & E Hall International Ltd for the warranty to remain valid.

Different connection arrangements are used depending on the application and the refrigerant, these are summarised in Fig 6.

#### 5.3. Liquid Injection Valve Selection

The liquid injection valve must be specifically designed for liquid injection cooling of screw refrigeration compressors. The valve may be thermostatically operated (e.g. Alco 935 series) or electronically via a temperature transducer, transmitter and controller.

The liquid injection valve must be sized to control discharge temperature at 90 °C. Select the valve as follows:

- Use the J & E Hall International HSS 3200 series compressor selection programme, available on CD, to obtain the cooling requirement for the required duty.
- Use the graphs in publication 2-122 Compressor Cooling to obtain the pressure difference for the operating conditions.
- Select the correct valve from manufacturer's literature.



#### Step 1

Plot the design operating conditions at **maximum load** on the envelope.

If the plotted point is above the line Liquid Injection Cooling Always Required, liquid injection cooling **is required at all loading conditions**. If the point is somewhere below the line, liquid injection cooling is not required at full load, proceed to Step 2.

#### Step 2

Plot the design operating conditions at **minimum (25 %) load** on the envelope, taking into consideration the reduction in condensing temperature, the increase in evaporating temperature and accounting for other compressors that may be running at maximum load.

If the plotted point is within the 25 % to 100 % area, then the compressor can run without liquid injection at minimum (25 %) load. Liquid injection is **not required** at any loading conditions **provided** the design operating conditions at 50 % load, when plotted, is within the 50 % to 100 % area.

If the minimum (25 %) load point is within the 50 % to 100 % area, then either:

- a) Liquid injection cooling will be necessary for operation at minimum (25 %) load, or
- b) If it is not intended to provide liquid injection, the compressor must be prevented from unloading below 50 %.

If the 50 % load design point is within the 75 % to 100 % area, then either:

- c) Liquid injection cooling will be necessary for operation at 50 % load, or
- d) If it is not intended to provide liquid injection, the compressor must be prevented from unloading below 75 %.

#### NOTES

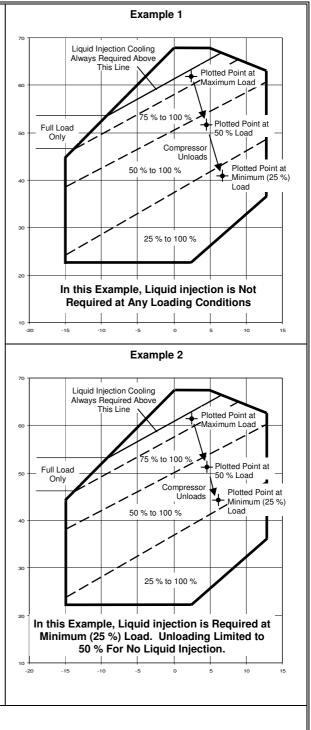
If, by this processes, it is decided that liquid injection is not required, as a precaution, the actual discharge temperature must be checked at all loading conditions.

If load limiting is applied, ask J & E Hall International for the correct slide valve position to achieve this.

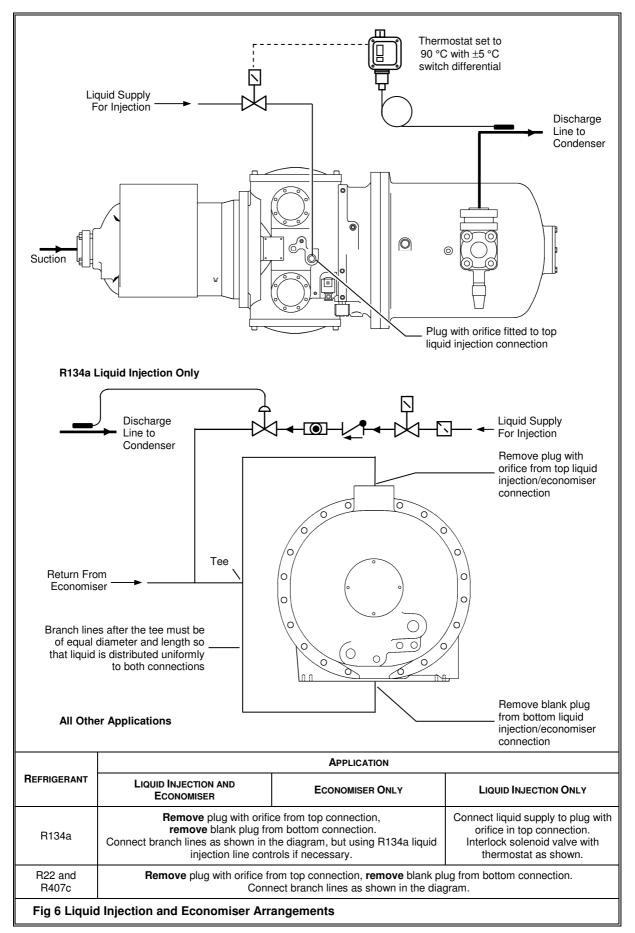
Compressor capacity is infinitely variable from 100 % to approximately 25 % of full load (depends on the operating conditions).

These load limit lines for liquid injection are approximate and are only intended to be used as a guide. More detailed analysis can be made using the compressor selection software.











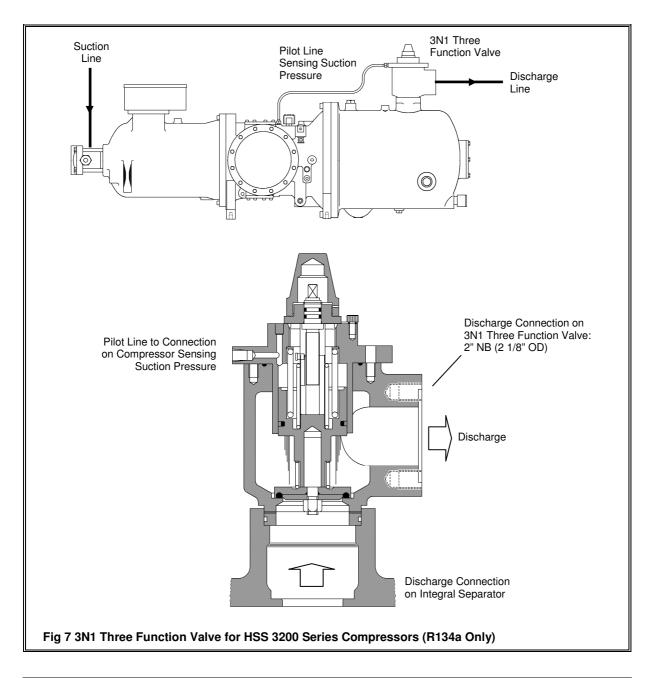
## 6. 3N1 Three Function Valve for HSS 3200 Series Compressors (R134a Only)

As an option, for R134a applications only, the discharge connection can be fitted with a specially designed valve which combines the following functions in one compact assembly.

- Discharge stop valve.
- Discharge check valve.
- Head pressure control valve (useful for applications using an air cooled condenser).

Note: when fitting or refitting the 3N1 valve, the pilot line between the valve and the connection provided on the compressor sensing suction pressure must be fitted. Failure to do so will prevent the valve from opening.

The 3N1 valve replaces the non-return valve otherwise fitted in the oil separator housing discharge.





## 7. Integration into the Refrigeration Circuit

The HSS 3200 compressor is an oil injected screw type. The integral oil separator is an impingement type. Oil separators are not 100 % efficient, so the system must be designed to return any oil carried over into the system from the separator, back to the compressor. The system should therefore be single circuit and direct expansion.

The suction return to the compressor must be dry gas in order to achieve full performance. Liquid return will be detrimental to performance although unlike reciprocating compressor is not harmful to the compressor in small quantities. However large quantities of liquid or oil returned to the compressor via the suction line can form an incompressible fluid in the rotor flutes with resultant damage to the compressor. Thus the system must be designed to prevent such occurrences.

#### 7.1. Oil System

The recommendation in 4. Oil Support System should be adhered to.

#### 7.2. Suction Line

The suction line should be designed to allow any build up of liquid to drain back to the evaporator. Refrigerant gas velocities should be sufficient to ensure recirculating oil is returned to the compressor.

#### 7.3. Liquid Separation in the Suction Line

If liquid is present in the suction line due to excessive carry over from the evaporator and velocities are low, separation of the liquid can occur. If Ubends are present in the suction line liquid can collect in these traps. If the flow rate is suddenly increased (due to sudden increase in compressor load) then this liquid can be carried through to the compressor as a slug. It is these large erratic slugs of liquid that are detrimental to the compressor rather than constant small amounts of liquid return.

#### 7.4. Discharge Superheat

Adequate discharge superheat is essential in order to prevent excessive liquid refrigerant dilution of the oil in the separator. If excessive refrigerant is present then oil viscosity will be reduced to an unacceptable level. The main problem however, is that for a small change in discharge pressure oil foaming and loss of oil from the separator can occur. Thus a safe minimum discharge superheat should be taken as 13.0 K for R134a and 20 K for R22 and R407c.

#### 7.5. Liquid Injection Lines

If liquid injection is required, different arrangements are used depending on the refrigerant; refer to 5. Compressor Cooling.

#### 7.6. Safety Requirements for Compressor Protection

There are a number of system pressures and temperatures which must be monitored to protect the compressor and obtain an overall view of performance; refer to Appendix 1 Compressor Data.



### 8. Electrical Connections

#### 8.1. Compressor Starting

The HSS 3200 series compressor motor is wired for star/delta starting. Soft-start or inverter drive starting methods can be accommodated using terminal links available from J & E Hall International.

# These links could be used for DOL starting, but this method of starting is not preferred by J & E Hall International.

Installing the terminal links requires modification to the terminal insulators; refer to J & E Hall International.

#### 8.2. Motor Wiring Connections

Terminal box wiring is illustrated in Fig 8 and Fig 9. Refer to Appendix 1 Compressor Data for motor data. The standard terminal box rating is IP54, IP65 available to special order.

#### 8.3. Thermistors

Compressor motor and discharge high temperature thermistors are fitted as standard and should be wired as illustrated in Fig 8.

#### 8.4. Capacity Control Solenoids

The solenoids must be connected to a suitable plant controller that will energise the appropriate coil to load or unload the compressor via changes to the operation of the system into which the compressor is fitted. The measured variable may be chilled water temperature, suction pressure, etc.

Power must be supplied to the solenoids via a suitable pulse timer with a minimum pulse length of 0.1 to 0.5 seconds, depending upon the accuracy of control required.

Operation of the solenoid with load is not linear, more pulses will be required at low loads for the same change in load compared with operation at high load.

#### 8.5. Linear Variable Displacement Transducer (LVDT)

The LVDT provides a continuous 4 to 20 mA slide valve position signal between minimum load (25 %) and maximum load (100 %). Slide valve position is not linearly proportional to the actual capacity of the compressor and greater slide travel is required at low load compared with high loads for the same change in load.

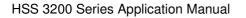
The LVDT is only available without calibration, this must be done on the controller. However, a signal conditioning module is available for applications where this is not possible.

External wiring connections are shown in Fig 10. Set up instructions for the signal conditioning module can be found in Appendix 6 Pepperl & Fuchs Signal Conditioning Module KFU8-USC-1.D Set-up.

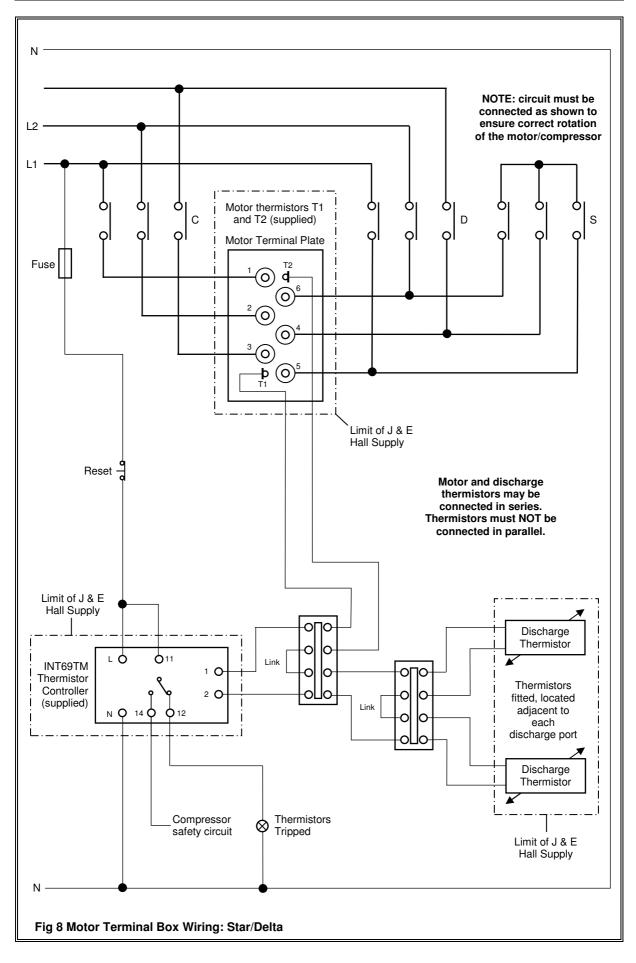
#### 8.6. Oil Low Level Sensor (Option)

External wiring connections are shown in Fig 11.

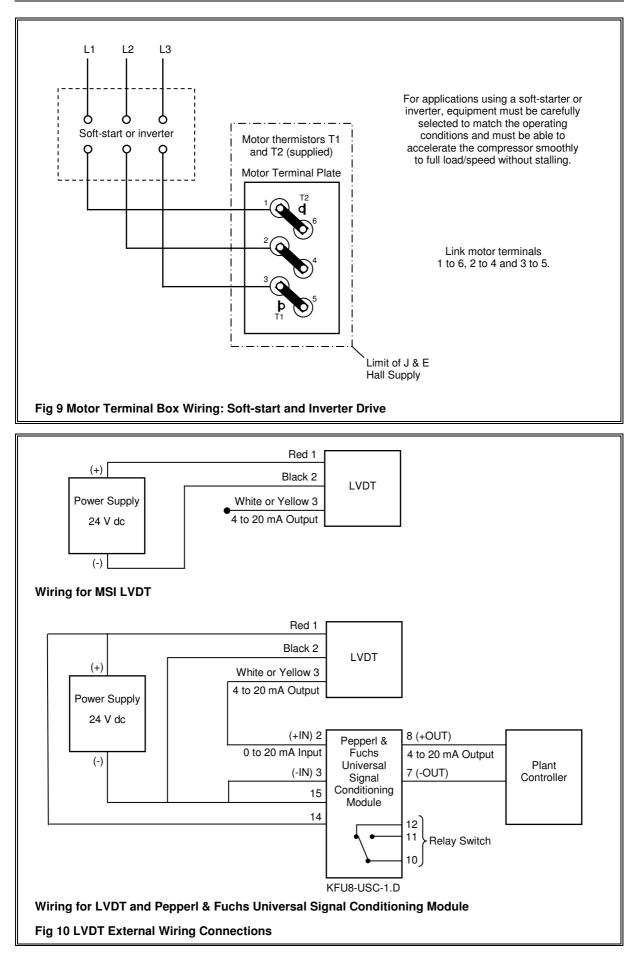
A conditioning relay is required to provide a volt-free contact.



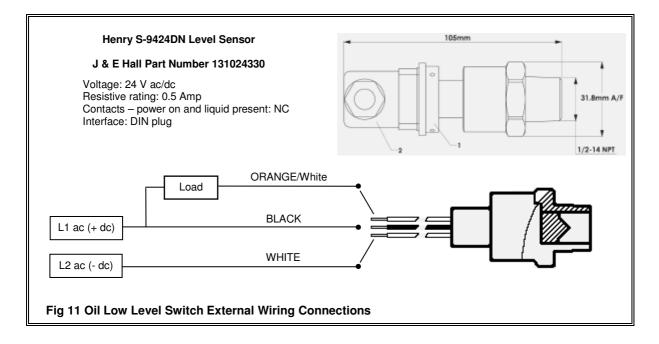














# Appendix 1 Compressor Data

- HSS 3200 Series: Compressor Model Nomenclature.
- HSS 3200 Series: Physical Data.
- HSS 3200 Series: Motor Data 50 Hz Operation.
- HSS 3200 Series: Motor Data 60 Hz Operation.
- HSS 3200 Series: Limits of Operation.
- Safety Requirements for Compressor Protection.
- HSS 3200 Series: Physical Dimensions and Connections -82 kW @ 50 Hz and 98 kW @ 60 Hz Motors.
- HSS 3200 Series: Physical Dimensions and Connections -138 kW @ 50 Hz and 166 kW @ 60 Hz Motors.



HSS 3200 Series: Compressor Model Nomenclature															
HallScrew	Application		Compressor		Capacity Control Slide V <sub>R</sub>	Lubricant	Motor Power (Nominal)	Motor Voltage	Refrigerant	Voltage (Auxiliary)	Capacity Indicator	Stop Valves and Flanges	Economiser Kit	Discharge Thermistor	
HS	S	3	2	Х	Х	х	х	Х	Х	Х	Х	х	Х	Х	
Applica	ation			S	Semi-h	ermeti	c compre	ssor for	air conc	ditioning	applicat	ion			
Compr	ressor			32X	Series	3200 1	win Star	16, 18,	20 or 21						
Capaci	ity Con	trol Sli	de V <sub>R</sub>	2	$2.2 V_{R}$										
				3	3.0 V <sub>R</sub>										
Lubrica	ant			Е	Ester o	il									
				М	Minera	l oil									
Motor I	Power	(Nomir	nal)	A 82/98 kW @ 50/60 Hz											
				H 138/166 kW @ 50/60 Hz											
Motor	Voltage	e		Q	400/460 V 3 ph 50/60 Hz			D	500/575 V 3 ph 50/60 Hz						
U			U	380 V 3 ph 60 Hz			V	230 V 3 ph 60 Hz							
				В	208 V 3	3 ph 60	) Hz			Х	Special voltage				
Refrige	erant			Α	R134a					С	R407c	;			
				В	R22					Х	Other				
Voltage	e (Auxi	liary)		1	115 V 1 ph 50/60 Hz			3	24 V dc						
				2	230 V	1 ph 50	)/60 Hz			4	24 V a	iC			
Capaci	ity Indi	cator		0	-		ndicator (s								
				D		-	cator (not								
				E		-	cator (not		ting + si	gnal cor	ditioning	g module	e)		
Stop V	alves a	and Fla	nges	A			lischarge								
				В			e and disc								
C					Suction flange and 3N1 three function discharge valve										
				D			lischarge	-							
				E		Suction stop valve and discharge flange									
		<i></i>		F			alve and	3N1 thr	ee tunc	tion disc	harge v	alve			
Econo	miser I	<b>Kit</b>		0	No eco										
<u> </u>				1			it (standa								
Discha	_		or 2/M/A/D/	1	Discha (standa		ermistor (	max ter	np 100 °	°C) and	Kriwan I	NT 69 TI	M contr	oller	

This describes a HallScrew 3218 twin star semi-hermetic compressor for air conditioning application fitted with 2.2  $V_R$  capacity control slide valves, supplied with mineral oil, fitted with a 82 kW motor suitable for 500/575 V 3 ph 50/60 Hz supply. Compressor for operation with R22. Solenoid/oil heater voltage 230 V 1 ph 50/60 Hz.



HSS 3200 Series: Physical Data										
Compressor Type	Single screw, inte	egral, semi-h	nermetio	).						
Compressor Rotation		Anti-clockwise looking on the motor end. Under no circumstances should the compressor run in the reverse direction.								
Method of Drive	Suction gas cool inverter drive. M									
Speed Range	Depends on the	supply frequ	ency, 5	0 Hz or 60	Hz, refe	r to Mo	tor D	ata.		
Physical Dimensions	Refer to Physical	Dimensions	and C	onnection	6.					
Capacity and Power	Refer to selection	n data.								
Capacity Control	Compressor capa (depends on the				)0 % to a	pproxin	natel	y 25 %	of full lo	oad
	Slide valve positi (LVDT). DIN plu				near Var	iable D	ispla	cemen	t Transo	lucer
Capacity Control Solenoids	115 V or 240 V a	c (other volt	ages av	ailable on	request)	. Term	inal I	box rati	ing IP65	j
Suction Strainer	Integral. 60 mes	h x 37 SWG								
Motor Terminal Box Rating	IP54 (standard),	IP65 (availal	ole to s	pecial orde	ər)					
Integral Oil Separator	250 W heater.									
	Sump capacity 1	8 litres.								
Swept Volume	SWEPT VOLU	ME (M <sup>3</sup> /HR)	н	SS 3216	HSS	3218	HS	SS 3220 HSS		S 3221
	Compressor runr (2 pole speed)	ning @ 50 H	z	286	34	3		415		471
	Compressor runr (2 pole speed)	ning @ 60 H	z	343	41	1		498		565
Weights		Co	MPRESS	OR				<sup>1</sup> V	VEIGHT	KG)
	HSS 3200i with 8	32 kW or 98	kW mot	or (all mo	dels)				719	
	HSS 3200i with 1	138 kW or 16	6 kW n	notor (all n	nodels)				840	
	3N1 three function	on valve (HS	S 3200	series on	ly)				12	
	<sup>1</sup> Excluding suction	on and discha	arge sto	p valves						
<sup>1</sup> Sound Pressure Levels	COMPRESSOR	TOTAL			CENTRE	FREQU	ENCY	/ – Hz		
@ 50 Hz (2 pole speed)	COMPRESSOR	D <b>B 'A</b> '	125	250	500	1к		2к	4к	8 K
	HSS 3216	78	63	75	71	74		69	65	63
	HSS 3218	78	63	76	71	75		70	67	66
	HSS 3220	79	63	76	74	76		72	68	68
	HSS 3221	79	63	76	74	76		72	68	68
important to remember that on a	<sup>1</sup> Sound pressure level data refers to free-field conditions at a distance of 1 metre from the compressor periphery. It is important to remember that on a specific installation the actual sound pressure level is considerably affected by the size and type of room, material of construction and plant design. Adjoining pipework, including suction, can have a very substantial									

Sound pressure levels given in dB refer to 2 x  $10^{\mbox{-}5}\,\mbox{N/m}^2\,\mbox{RMS}.$ 



				•			
Compressor Running @ 50 Hz (2980 RPM)		HSS 3216		HSS 3218			
Motor nominal output (kW)	8	2	138	82		138	
Refrigerant	R134A	R407c	AND R22	R134A	R134A R407c		
Capacity control slide valve $V_R$ (refer to Appendix 3 for limits of operation)	2.2/3.0	2.2	3.0	2.2/3.0	2.2	3.0	
Motor maximum input (kW)	73	73 83 110		88	99	132	
Maximum running current (A) @ 400 V	123	135	179	146	159	211	
Starting current (locked rotor) in Y (A) @ 400 V	28	38	455	288		455	
Starting current (locked rotor) in $\Delta$ (A) @ 400 V	90	)6	1480	906		1480	
Standard voltage range (V)	(V) 400 ± 10 %						
Compressor Running @ 50 Hz (2980 RPM)		HSS 3220			HSS 3221		
Motor nominal output (kW)	8	2	138	82		138	
Refrigerant	R134A	R407c	AND R22	R134A	R407c	AND R22	
Capacity control slide valve $V_R$ (refer to Appendix 3 for limits of operation)	2.2/3.0	2.2	3.0	2.2/3.0	2.2	3.0	
Motor maximum input (kW)	108	120	160	122	135	181	
Maximum running current (A) @ 400 V	177	191	253	199	215	286	
Starting current (locked rotor) in Y (A) @ 400 V	288 455 288			38	455		
Starting current (locked rotor) in $\Delta$ (A) @ 400 V	906 1480 906			06	1480		
Standard voltage range (V)			400 ±	10 %			

# HSS 3200 Series: Motor Data – 50 Hz Operation





Compressor Running @ 60 Hz (3575 RPM)		HSS 3216			HSS 3218			
Motor nominal output (kW)	9	8	166	98		166		
Refrigerant	R134A	R134A R407c AND R		R134A	R407c	AND R22		
Capacity control slide valve V <sub>R</sub> (refer to Appendix 3 for limits of operation)	2.2/3.0	2.2	3.0	2.2/3.0	2.2	3.0		
Motor maximum input (kW)	88	100	132	106	119	158		
Maximum running current (A) @ 460 V	122	138	182	146	163	216		
Starting current (locked rotor) in Y (A) @ 460 V	28	35	461	285				
Starting current (locked rotor) in $\Delta$ (A) @ 460 V	89	893 1499		893		1499		
Standard voltage range (V)	Standard voltage range (V) 460 ± 10 %							
Compressor Running @ 60 Hz (3575 RPM)		HSS 3220			HSS 3221			
Motor nominal output (kW)	9	8	166	9	166			
Refrigerant	R134A	R407c	AND R22	R134A	R407c	AND R22		
Capacity control slide valve V <sub>R</sub> (refer to Appendix 3 for limits of operation)	2.2/3.0	2.2	3.0	2.2/3.0	2.2	3.0		
Motor maximum input (kW)	130	144	192	146	162	217		
Maximum running current (A) @ 460 V	177	197	263	201	222	297		
Starting current (locked rotor) in Y (A) @ 460 V	28	35	461	28	85	461		
Starting current (locked rotor) in $\Delta$ (A) @ 460 V	89	93	1499	89	1499			
Standard voltage range (V)			460 ±	10 %		•		

# HSS 3200 Series: Motor Data – 60 Hz Operation



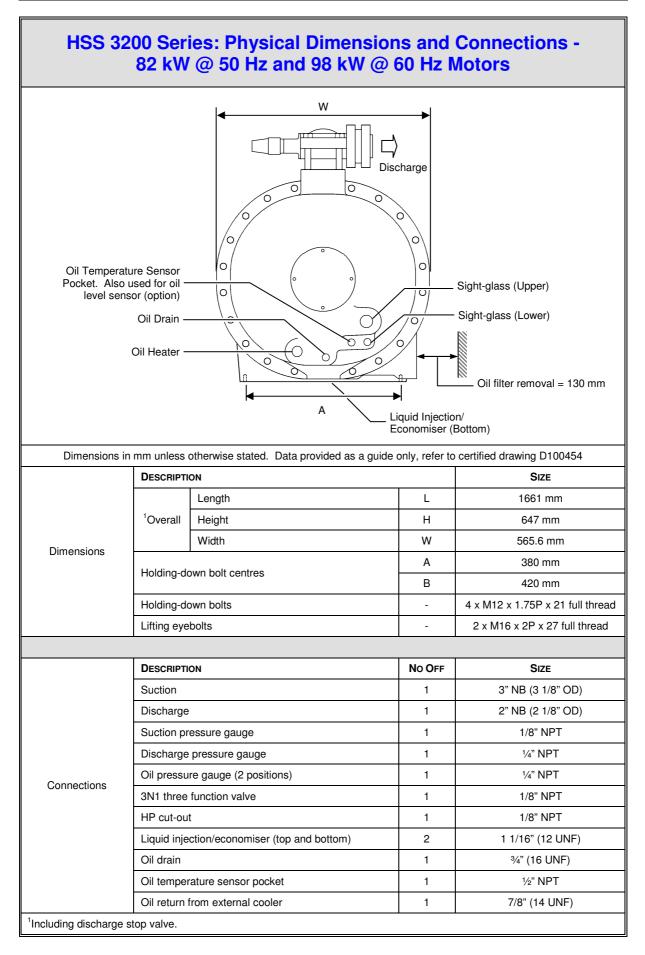
HSS 3200 Series: Limits of Operation										
Pressure LimitsThe pressure limits detailed below MUST NOT be exceeded during installation, commissioning or operation of the plant. Refer to Appendix 3 Limits of Operation Envelopes for further details.										
	R134a R22 R407c									
Maximum Design Pressures	<sup>1</sup> High side/low side test pressure		23.6 bar g	32.9 bar g	32.9 bar g					
<sup>2</sup> Operational Pressures	Maximum compressor operating suction pressure	2.2 or 3.0 $V_R$	3.5 bar g	6.4 bar g	6.0 bar g					
	Maximum compressor operating d pressure	19.4 bar g	27.9 bar g	29.6 bar g						
	Maximum compressor operating p differential (discharge – suction)	Maximum compressor operating pressure differential (discharge – suction)								
	Minimum compressor operating pu differential at minimum load	essure	2.0 bar	3.0 bar	3.0 bar					
Temperature Limits										
Temperature Limits	Discharge temperature			00 °C (standaı 20 °C (specia	,					
	Discharge minimum superheat R134a = 13.0 K									
	R22 and R407c = 20.0 K									
compressor during system str	jected to pressures higher than those rength pressure testing. ay be less than those applicable to the		a may require	isolation of	the					



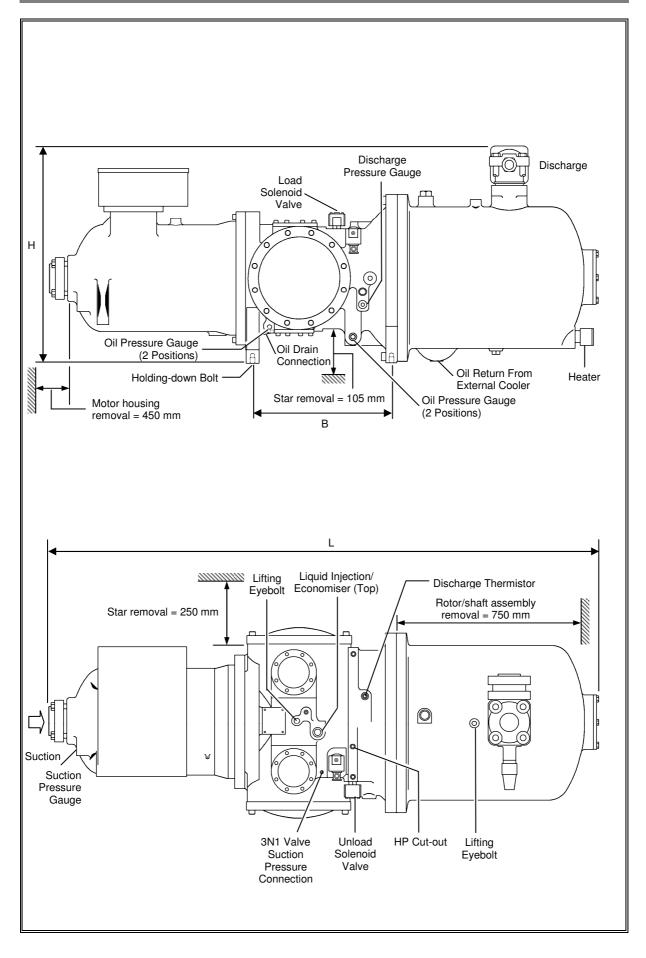
Parameter	Trip	Device	Setting	Remarks
Discharge pressure	High	HP cut-out	According to the operating conditions	Connected to compressor discharge
Discharge pressure	Low	Pressure control or pressure transducer and programmable controller with suitable analogue inputs	According to the operating conditions	-
Discharge temperature	High	Thermistor (fitted as standard)	100 °C (standard) 120 °C (special)	For 120 °C (special) refer to J & E Hall International.
				The discharge thermistors can be wired in series with the motor thermistor; refer to Fig 8.
Suction pressure	Low	LP cut-out or pressure transducer and programmable controller with suitable analogue inputs	According to the operating conditions	Prevents operation at low suction gauge pressures
Oil differential pressure 1	Low	Preferred method:	Pressure ratio 2	Oil pressure should be twice suction pressure (absolute)
Oil injection pressure - suction pressure		Pressure transducers and programmable controller with suitable analogue inputs		30 second delay required on starting only
		Alternative method: Differential pressure switch; refer to Fig 4	Value of the differential to be equal to the value of the highest operational suction pressure (absolute)	30 second delay required on starting only
Oil differential pressure 2 Discharge pressure - oil	High	Differential pressure switch (refer to Fig 4) or pressure transducers and	2 bar (standard) 3 bar (maximum)	Should be approximately 1 bar above difference when filter is new.
injection/lubrication pressure		programmable controller with suitable analogue inputs		ODP2 is not mandatory but is recommended to detect when the oil filter is becoming blocked and it is time to renew the filter element.
Oil separator oil level	Low	Level switch or sensor	Trip on low level	Time delay (5 secs max) required during operation to prevent spurious trips
Oil temperature	High	Thermistor or HT cut-out	80 °C	Mandatory requirement if compressor fitted with external oil cooling
Compressor motor high temperature	High	Thermistor (fitted as standard)	-	The motor thermistor can be wired in series with the discharge thermistor; refer to Fig 8.
Compressor motor current	High	Current limiter, or current transformer and programmable controller with suitable analogue inputs	Set according to the compressor motor size	Prevents operation above the maximum rated motor power

# Safety Requirements for Compressor Protection

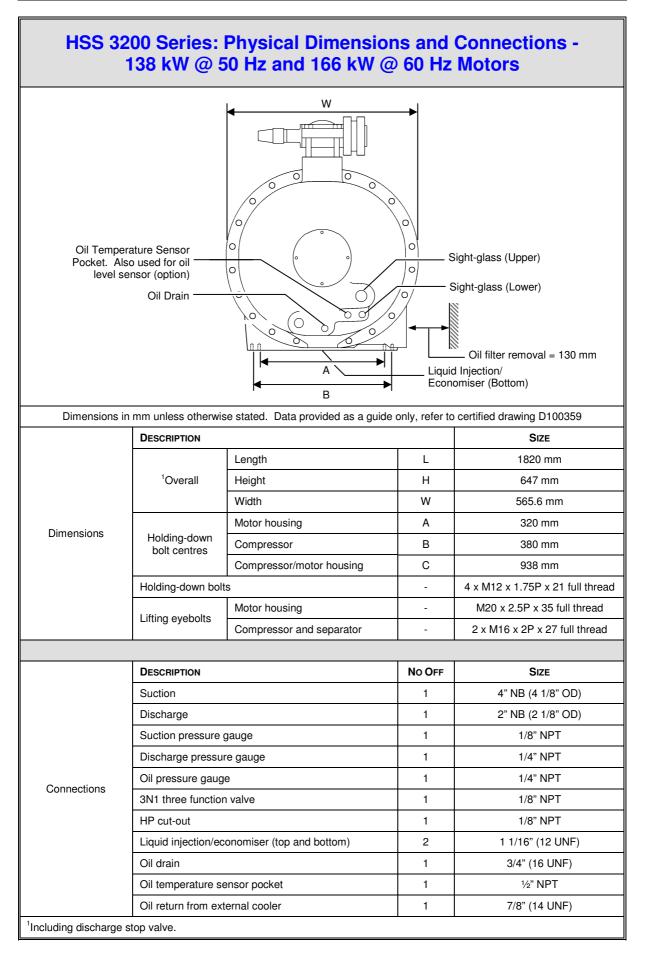




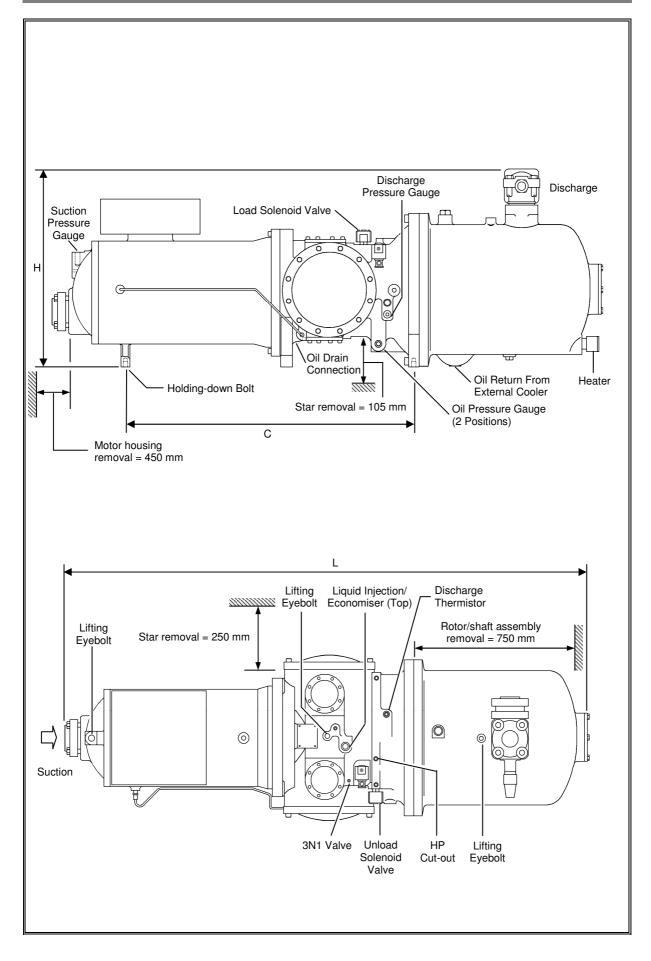




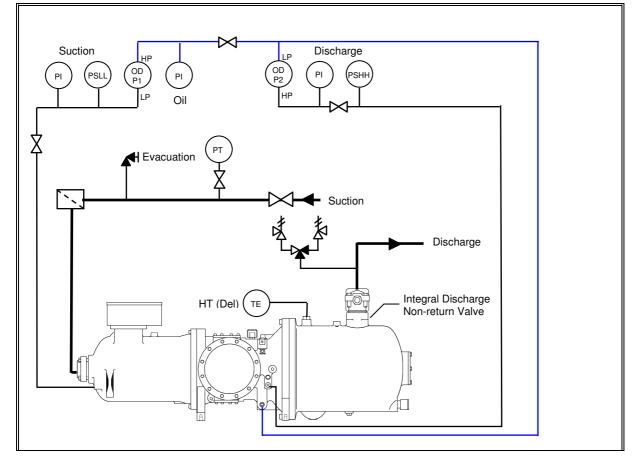








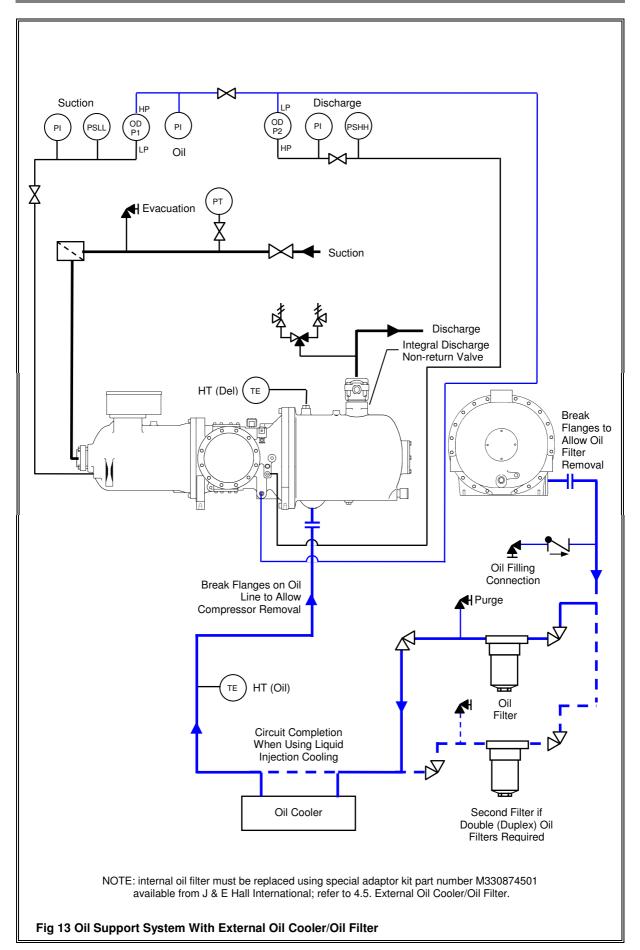




## Appendix 2 Oil Support System Schematic Flow Diagrams

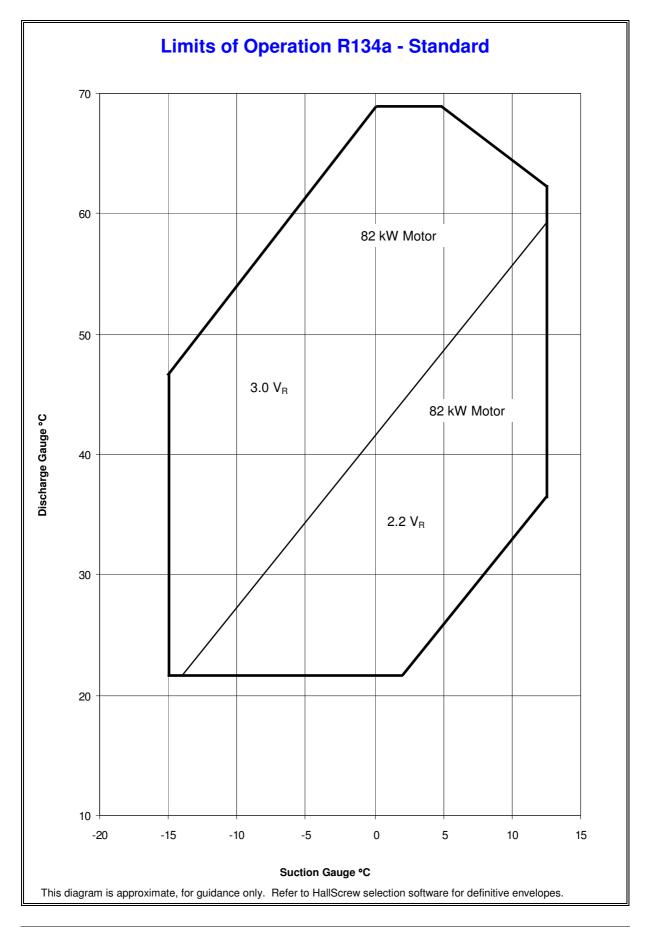
Normally Ope	en Locked Open Normally Closed Noi a		Normally Closed and Capped				
$\bowtie$	$\bowtie$	M	M	Valve, straight through			
Ø	Ø	7	J	Valve, right angle			
	Strainer		•	Non-return valve			
	Dual relief valve (to atmosphere)		PT	Pressure Transmitter			
PI	Pressure Indication (p transducer)	ressure gauge or	ODP	Oil Differential Pressure Switch			
PSHH	Pressure Switch High (discharge high pressure cut-out or transducer)				LLS	Low Level Switch (optional)	
PSLL	Pressure Switch Low (suction low pressure cut-out or transducer)		e (TE)	Thermistor or high temperature cut-out			
Fig 12 Oil	Fig 12 Oil Support System						



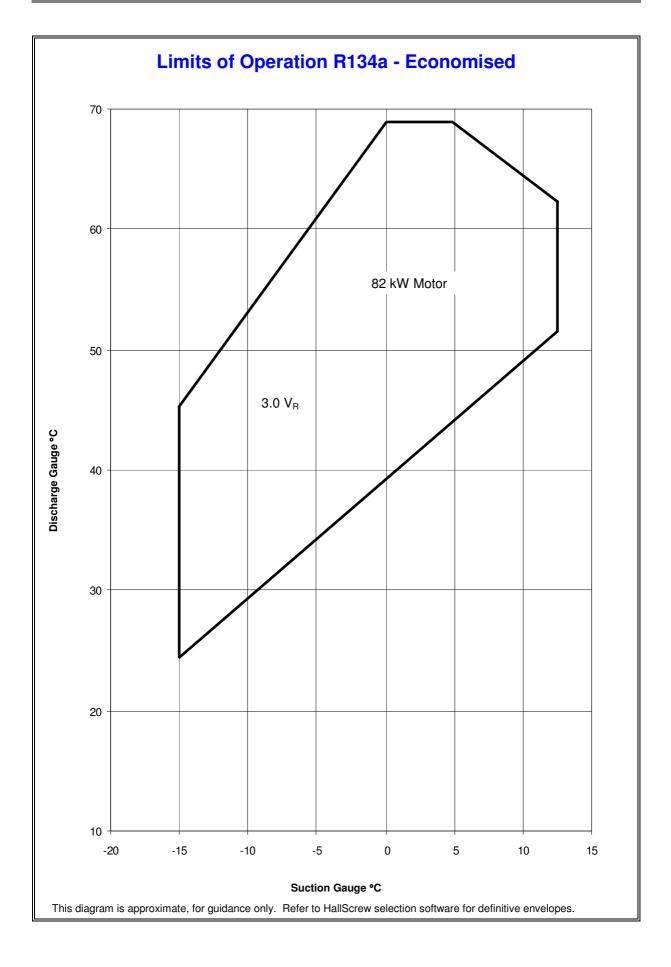




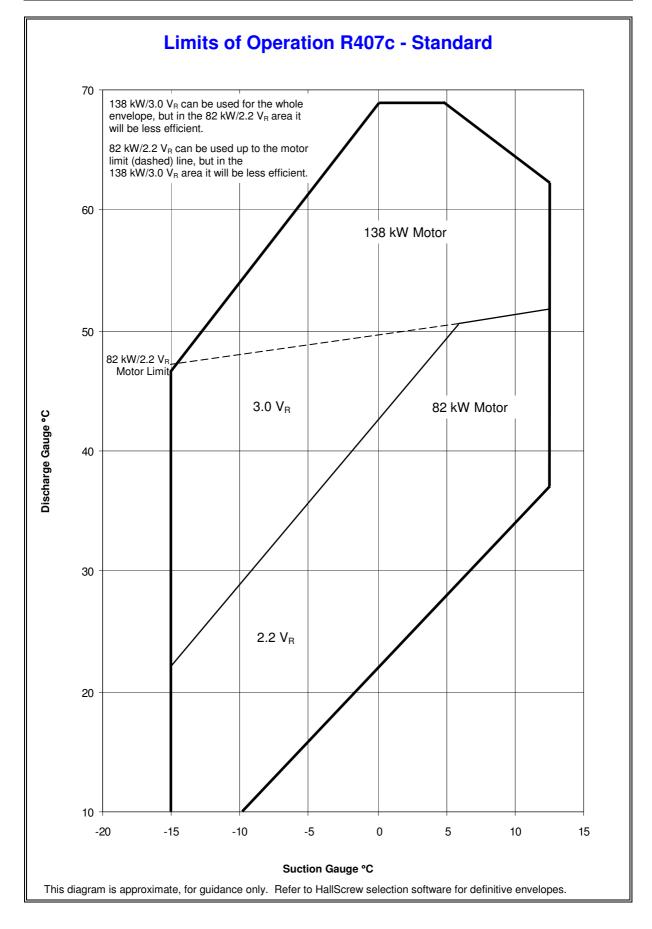
## **Appendix 3 Limits of Operation Envelopes**



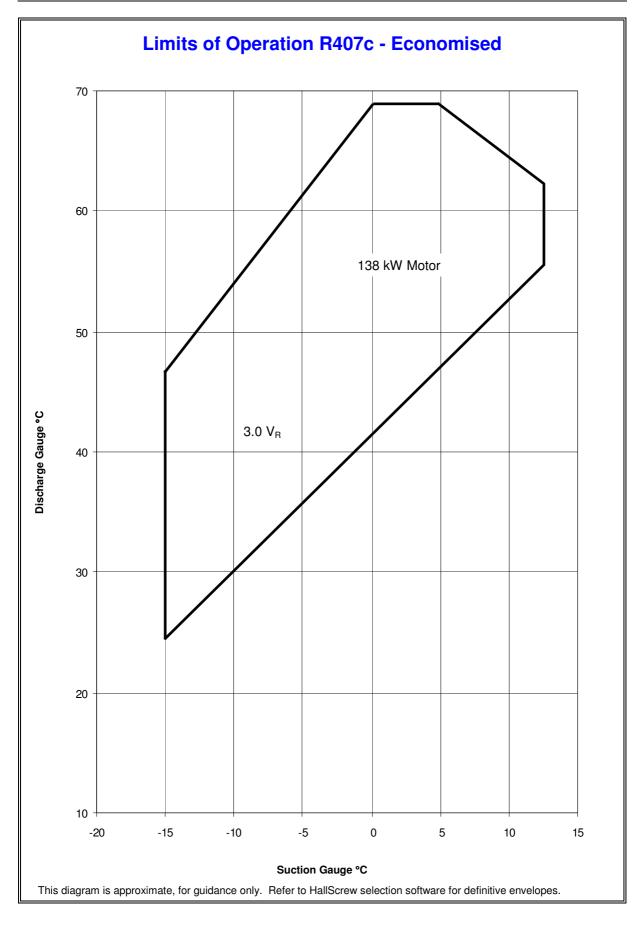




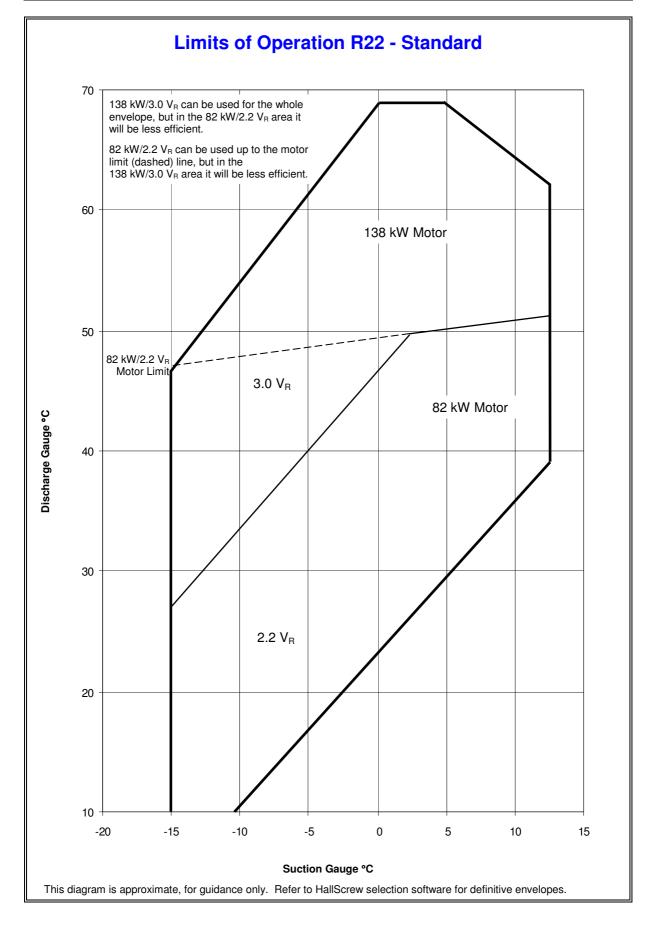




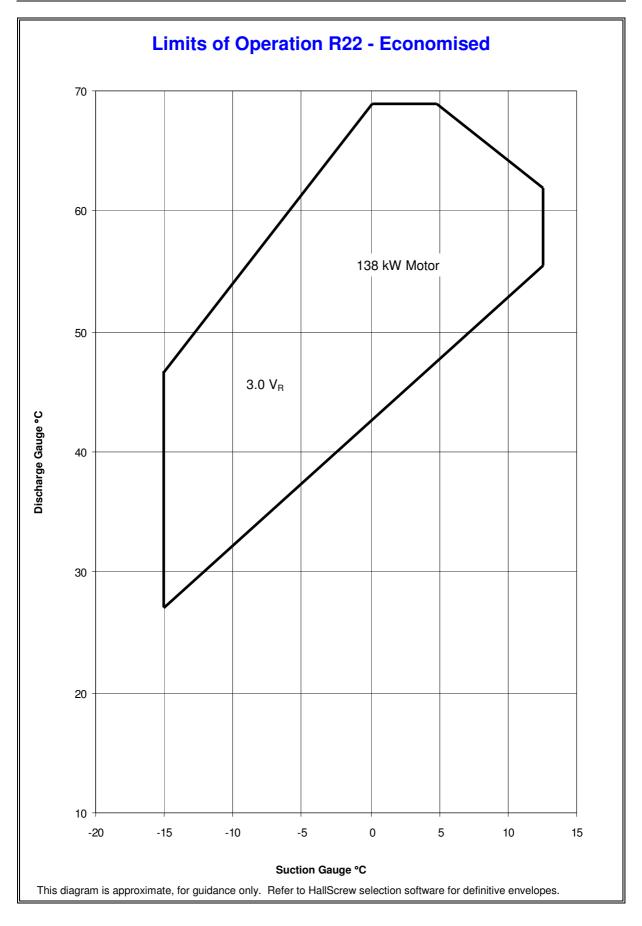






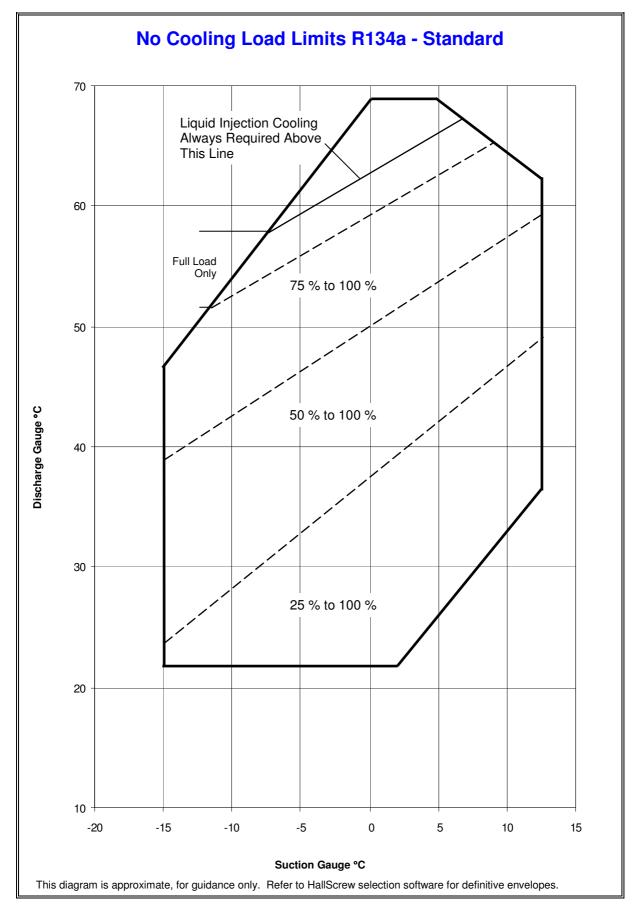




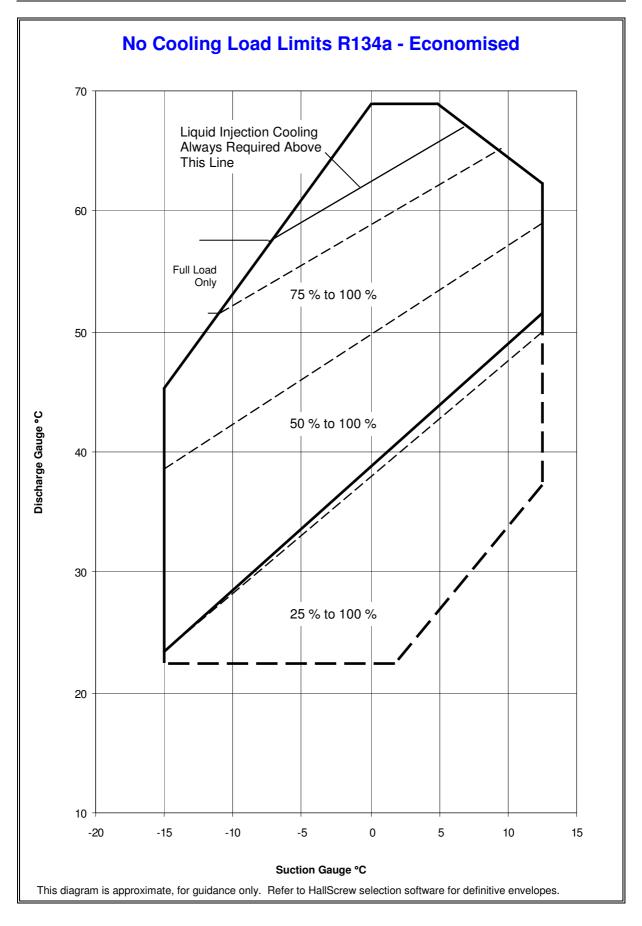




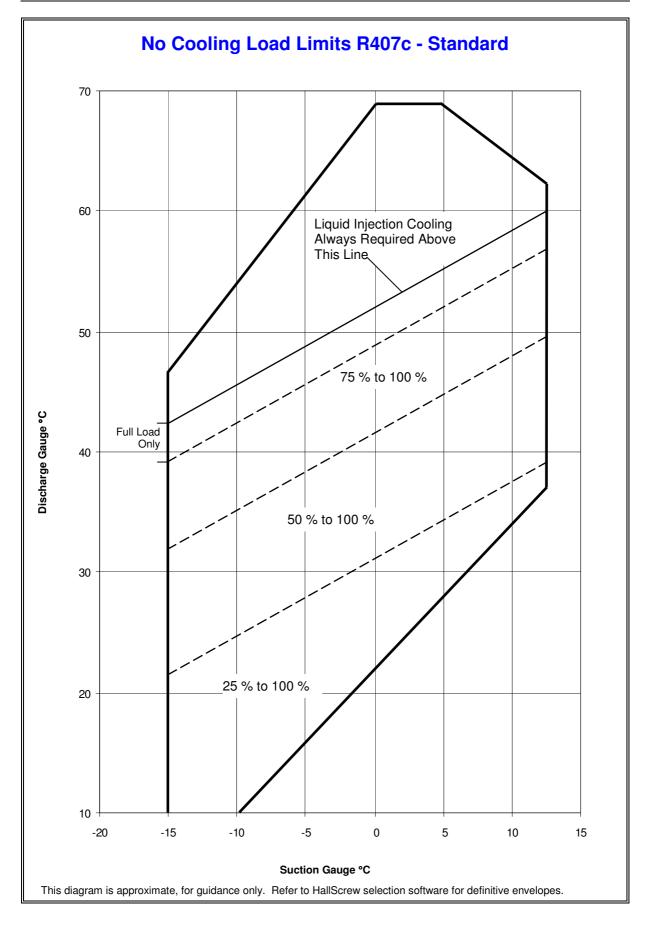
## Appendix 4 No Cooling Load Limits



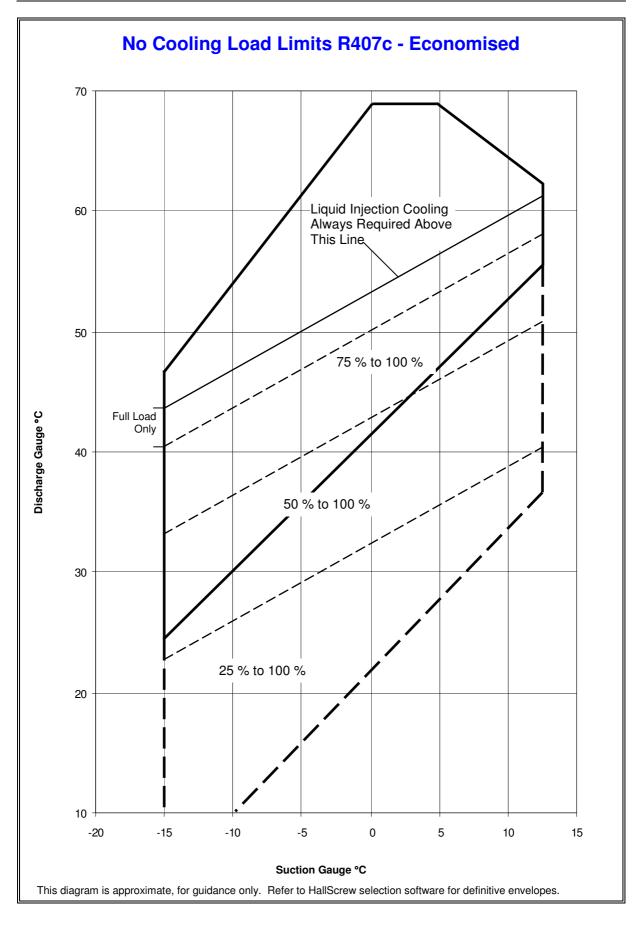




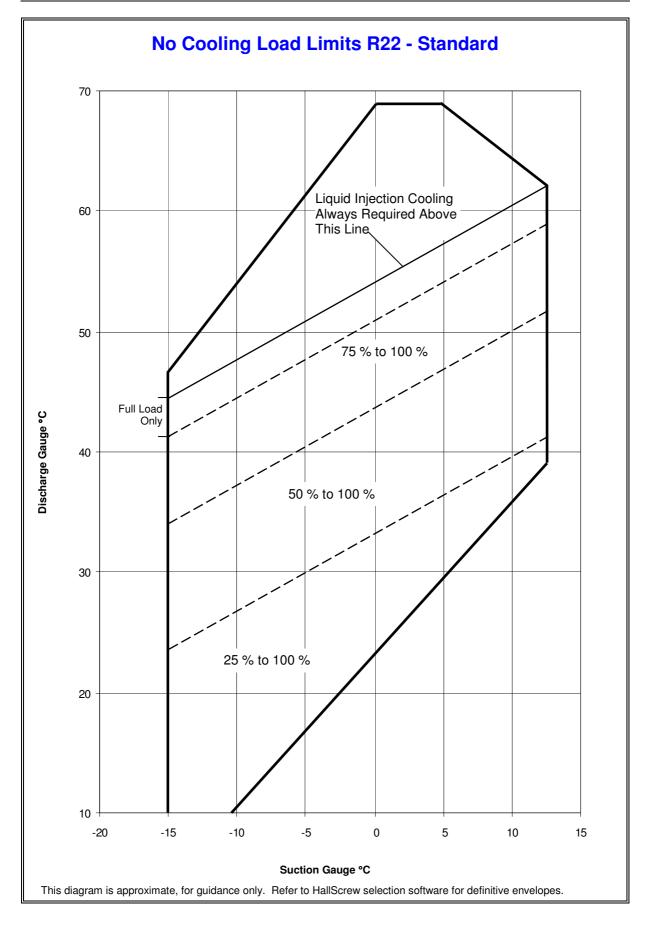




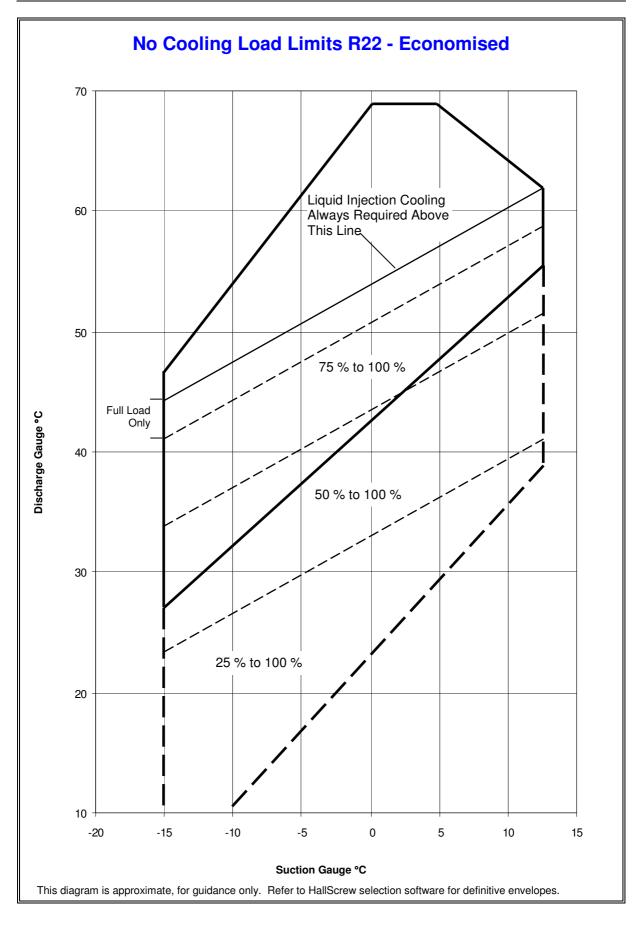














## **Appendix 5 Compressor Performance Data**

For detailed selection use the J & E Hall International HallScrew compressor selection software, available on CD.

Continuous research and development may necessitate changes to specifications and data in this Application Manual and the J & E Hall International Compressor Selection Software.

### Subcooling & Superheat Correction Factors

The performance data is based on 5.0  $^{\circ}$ C suction superheat and 5.0  $^{\circ}$ C liquid subcooling.

The suction superheat is assumed to be usefully obtained. Such superheat can be obtained in the evaporator or in a liquid to suction heat exchanger or similar vessel in the refrigeration circuit producing a beneficial effect.

The approximate effect of an increase in useful suction superheat is an increase in capacity of 0.17 % for every additional 1.0 °C superheat.

Non usefully obtained superheat (such that might be picked up in the suction line due to heat exchange with the environment) will have a detrimental effect on performance.

The approximate effect is a loss in performance of approximately 0.7 % for each additional 1.0  $^{\circ}$ C of non useful suction superheat.

It is important to ensure adequate suction superheat. Insufficient superheat can result in liquid carry over into the compressor, reducing performance and also resulting in inadequate discharge superheat for satisfactory oil separation.

Additional subcooling will have a beneficial effect on the system performance.

The approximate effect of an increase in liquid subcooling is an increase in capacity of 1.1 % for every additional 1.0 °C subcooling.

If the useful superheat is obtained in a suction to liquid heat exchanger then only the effect of the increase in suction superheat should be taken in to account. Otherwise the effect on performance will be added twice. Using the increase in suction superheat also includes the effect of the change in specific volume at the compressor suction.

## Appendix 6 Pepperl & Fuchs Signal Conditioning Module KFU8-USC-1.D Set-up

# Basic Set up for 4 mA and 20 mA Output Values at Minimum and Maximum Slide Valve Positions

Refer to Table 2.

The KFU8-USC-1.D module can be used simply to calibrate the output from the MSI LVDT to provide 4 mA and 20 mA signals, at the compressor minimum and maximum slide valve positions respectively, by following the instructions in Table 2. Setting the 'Start Value' (at minimum load) and setting the 'End Value' (at maximum load) are independent processes. The End Value setting can be made at any time after the Start Value setting. The values can be reset at any time. If necessary, the unit can be reset to the factory settings by following the instructions in the Pepperl & Fuchs manual included with the unit.

# Setting the Display to Read 0 at Minimum Load and 100 at Maximum Load

Refer to Table 3.

**This procedure is optional** and not necessary for the basic calibration of the signal from the MSI LVDT, however it is useful for setting a slide valve position for the relay switch. It also provides a visual display of the slide position as if it were a percentage value.

NOTE: although '%' is a unit option in the module, this cannot be used as the units for this application because it has a pre-programmed function which does not allow the required 'Factor' to be set up (also 'mA' cannot be used as a unit because this is the same as the input units). It is therefore recommended that 'l' is used for the units; this allows the 'Zero' and 'Factor' to be set to give the 0 to 100 numerical values required even though the actual unit is not meaningful.

Unless the 'units' are reconfigured, the value displayed on the module is always the actual **input value** in mA from the LVDT. This is not particularly meaningful for the user.

To set the relay switch trip point, the value must be in the units displayed, so if not reconfigured, this would need to be calculated from the input mA for a given slide valve position. It is therefore easier to set the trip point if the display reads 0 at minimum load and 100 at maximum load, then the switch point trip value can be set as if it were a percentage slide valve position.

### Setting the Relay Switch Value

Refer to Table 4.

Once the display units have been reconfigured to 'l' and the display values at minimum and maximum load slide positions are 0 and 100 respectively, the switch (Trip) point can be set as a value as if it were a percentage. The 'Hysteresis' value can also be set as equivalent to a percentage. Depending on how it is required for the switch hysteresis to operate with rising and falling values, the module can be configured accordingly; refer to the note at the bottom of Table 4. This is also demonstrated fully in the Pepperl & Fuchs manual included with the unit).



KFU	J8-USC-		Ļ		1 2 3 KFUB-USC- 1.0 ESC CK 7 8 9 10 11 12 13 14 15 Display	
Slide \ Posit		Action	Input		Output	
FUSI	.1011		Display	Comment	Value	Comment
Minimur	n load	Record value displayed on unit	6.235 mA	For example	6.235 mA	Start
		Press buttons on Display:				
		ESC + OK (together)	Unit			
			Input			
			Output			
		OK	Relay			
			Analogue Out			
		OK	Characteristic			
		OK	0 to 20 mA	'Flashing'		
			4 to 20 mA NE4	'Flashing'	6.235 mA	
		OK	4 to 20 mA NE4	Set (saved)	9.0 mA	Temporary value
		ESC	Characteristic			
		4	Start Value			
		OK	Numeric			
			Teach In			
		OK	6.235 mA	'Flashing'	9.0 mA	
		OK	6.235 mA	Start value saved	4 mA	Minimum load se
		ESC	Teach In			
		ESC	Start Value			
		ESC	Analogue Out			
		ESC	Output			
						1



Slide Valve	Action Record value displayed on unit	Input		Output	
Position		Display	Comment	Value	Comment Temporary value
Maximum load		15.76 mA	For example	15.1mA	
	Press buttons on Display				
	ESC + OK (together)	Unit			
		Input			
		Output			
	ОК	Relay			
		Analogue Out			
	ОК	Characteristic			
		Start Value			
		End Vlaue			
	ОК	Numeric			
		Teach In			
	ОК	15.76 mA	'Flashing'	15.1 mA	
	ОК	15.76 mA	End value saved	20 mA	Maximum load se
	ESC	Teach In			
	ESC	End Value			
	ESC	Analogue Out			
	ESC	Output		ł	
Maximum load	ESC	15.76 mA	Default screen	20 mA	Finish
Minimum load		6.235 mA		4 mA	
	the 'Start Value' (at minim e End Value setting can b				independent



This pr KFU8-US		led for easy set up	b of the relay switch point (if used); refer to 1 2 3 ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ ■	Table 4
Slide Valve Position	Action		Output Value	
<sup>1</sup> Min load	<u> </u>	Display	Comment	4 mA
win load	Duese the fellowing butters	6.235 mA	For example	4 MA
	Press the following buttons	Unit		
	ESC+OK (together) OK	mA	'Flashing'	
		<sup>2</sup> %	'Flashing'	
		78 <sup>2</sup>	'Flashing'	
	ОК	2	Unit set	
	ESC	Unit		
		Input		
	ОК	Туре		
		Zero		
	ОК	4.000	'Flashing'	
	▲ ▼	6.23 mA	Set value = min load input value	
	OK	6.23 mA	Zero set	
	ESC	Zero		
		Factor		
	ОК	1.000	'Flashing'	
	▲ ▼	10.49	Set value = 100/(15.765 - 6.235)	
	ОК	10.49	Multiplying factor set	
	ESC	Factor		
ł	ESC	Input		+
Min load ESC		0.000	% slide valve setting	4 mA
Max load		100.0	% slide valve setting	20 mA

<sup>1</sup>Operation can be done with the slide valve in any position. <sup>2</sup>The unit of % cannot be chosen for this application because of the special functionality given to it inbuilt in the unit (for example, if % is chosen as the unit then the required Factor cannot be set). Therefore it is suggested that 'l' is chosen as the unit for simplicity although it must be recognised that for this application the unit does not any real meaning, i.e. the value is dimensionless or can be interpreted as a percentage value.

#### Table 3 Setting the Display to Read 0 at Minimum Load and 100 at Maximum Load



Set t		ad and 100 at max	imum load before setting the relay switch the formula of the formu	value	
Slide Valve Position	Action	Display	Input Comment	Output Value	
<sup>1</sup> Min load		0.000	For example		
	Press the following buttons				
	ESC + OK (together)	Unit			
	▼	Input			
	<b>V</b>	Output			
	OK	Relay			
	ОК	<sup>2</sup> MIN/MAX	Default set to MIN		
	▼	Trip			
	OK	102.4	For example 'Flashing'		
	▲▼	70.00	Set value (for example) 'Flashing'		
	OK	70.00	Trip value set		
	ESC	Trip			
	▼	Hysteresis			
	ОК	20.98	For example 'Flashing'		
		2.000	Set value (for example) 'Flashing'		
	ОК	2.000	Hysteresis value set		
	ESC	Hysteresis			
	ESC	Relay			
	ESC	Output			
Min load	ESC	0.000		4 mA	

<sup>1</sup>Operation can be done with the slide valve in any position. <sup>2</sup>MIN setting will make/break switch at Trip value when value is falling. When value is rising, the switch will break/make at the Trip value + Hysteresis value. MAX setting will make/break switch at Trip value when value is rising. When value is falling, the switch will break/make at the Trip value – Hysteresis value; refer to pages 18 and 19 of the Pepperl & Fuchs manual included with the unit.

Table 4 Setting the Relay Switch Value





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